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Fractional Calculus Operators in Physical Models: A Comprehensive Interpretation

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ABSTRACT

Fractional calculus provides a powerful framework for modeling complex physical systems. This paper presents a comprehensive review of fractional calculus operators, their associated physical models, and an interpretation of the parameters within these models. The study covers a wide range of fractional operators, including Riemann-Liouville, Caputo, Grünwald-Letnikov, and many others, illustrating their applications across different scientific and engineering domains.

Keywords: Fractional calculus; Highly generalized fractional differential equations; Left Atangana-Baleanu fractional derivative; Left-sided Hadamard fractional derivative; Left-sided Caputo-type Hadamard fractional derivative; Fractional-order dynamics; Memory effects; Long-range interactions; Anomalous diffusion; Existence and uniqueness of solutions; Asymptotic behavior; Stability analysis; Mathematical modeling; Control strategies; Scientific applications; Engineering applications

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INTRODUCTION

Fundamental Concepts of Fractional Calculus

[1-38]

Definition and Interpretation of Fractional Derivatives and Integrals

Fractional calculus generalizes classical calculus by extending the concept of differentiation and integration to non-integer orders. The fractional derivative and integral are the core concepts, each with multiple definitions depending on the approach. Below, we discuss some of the most widely used definitions.

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Riemann-Liouville Fractional Integral

The Riemann-Liouville fractional integral of order $\alpha \in \mathbb{R}^+$ of a function f(t) is defined as:

$$I_{a+}^{\alpha}f(t) = \frac{1}{\Gamma(\alpha)} \int_{a}^{t} (t-\tau)^{\alpha-1} f(\tau) d\tau, \quad t > a,$$

where $\Gamma(\alpha)$ is the Gamma function, defined as:

$$\Gamma(\alpha) = \int_0^\infty x^{\alpha - 1} e^{-x} dx.$$

Remark 1. The Riemann-Liouville fractional integral is a generalization of the n-fold integral when $\alpha = n \in \mathbb{N}$: $I_{a+}^n f(t) = \frac{1}{(n-1)!} \int_a^t (t-\tau)^{n-1} f(\tau) d\tau$.

Riemann-Liouville Fractional Derivative

The Riemann-Liouville fractional derivative of order $\alpha \in \mathbb{R}^+$ is defined as:

$$D_{a+}^{\alpha}f(t) = \frac{d^n}{dt^n} I_{a+}^{n-\alpha}f(t),$$

where $n = [\alpha]$ and $I_{\alpha+}^{n-\alpha} f(t)$ is the Riemann-Liouville fractional integral of order $n - \alpha$.

Lemma 1. If f(t) is an absolutely continuous function on [a,b] and $f^{(k)}(t) \in L^1[a,b]$ for k=0,1,...,n-1, then the Riemann-Liouville fractional derivative satisfies: $D_{a+}^{\alpha}f(t) = \frac{1}{\Gamma(n-\alpha)}\frac{d^n}{dt^n}\int_a^t \frac{f(\tau)}{(t-\tau)^{\alpha-n+1}}d\tau$.

Proof. This result follows directly from the definition of the Riemann-Liouville fractional derivative and the fundamental theorem of fractional calculus, which links fractional integrals and derivatives. \Box

Caputo Fractional Derivative

The Caputo fractional derivative of order $\alpha \in \mathbb{R}^+$ is defined as:

$${}^{C}D_{a+}^{\alpha}f(t)=I_{a+}^{n-\alpha}\frac{d^{n}}{dt^{n}}f(t),$$

where $n = [\alpha]$

Theorem 2. For a sufficiently smooth function f(t), the Caputo fractional derivative can be expressed as: ${}^CD_{a+}^{\alpha}f(t)=\frac{1}{\Gamma(n-\alpha)}\int_a^t \frac{f^{(n)}(\tau)}{(t-\tau)^{\alpha-n+1}} d\tau$.

Remark 2. The Caputo derivative is particularly useful in physical applications because it allows for the incorporation of classical initial conditions, such as f(a), f'(a), ..., $f^{(n-1)}(a)$.

Grünwald-Letnikov Fractional Derivative

The Grünwald-Letnikov fractional derivative of order $\alpha \in \mathbb{R}^+$ is defined as the limit:

$$D_{GL}^{\alpha}f(t) = \lim_{h \to 0^+} \frac{1}{h^{\alpha}} \sum_{k=0}^{\left\lfloor \frac{t-a}{h} \right\rfloor} (-1)^k {\alpha \choose k} f(t-kh),$$

where $\binom{\alpha}{k}$ is the binomial coefficient generalized to non-integer α .

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Lemma 3. The Grünwald-Letnikov derivative is equivalent to the Riemann-Liouville fractional derivative under appropriate conditions, specifically when the function f(t) is sufficiently smooth and the step size h is small.

Proof. This equivalence can be established by showing that the difference between the Grünwald-Letnikov definition and the Riemann-Liouville fractional derivative vanishes as $h \to 0^+$, utilizing the Taylor series expansion of f(t). \Box

Properties of Fractional Operators

Fractional operators exhibit properties that generalize those of classical calculus, but with significant differences that have important implications in modeling.

Linearity

Fractional derivatives and integrals are linear operators. For any two functions f(t) and g(t), and constants a and b, we have:

$$D^{\alpha}(af(t) + bg(t)) = aD^{\alpha}f(t) + bD^{\alpha}g(t),$$

$$I^{\alpha}(af(t) + bg(t)) = \alpha I^{\alpha}f(t) + bI^{\alpha}g(t).$$

Remark 3. The linearity of fractional operators is similar to classical operators, which is essential for superposition in physical models.

Semigroup Property

For the Riemann-Liouville fractional integral, the semigroup property holds:

$$I_{a+}^{\alpha}I_{a+}^{\beta}f(t)=I_{a+}^{\alpha+\beta}f(t),\quad \alpha,\beta>0.$$

Corollary 4. The semigroup property does not generally hold for fractional derivatives. Specifically, for the Riemann-Liouville derivative, $D_{a+}^{\alpha}D_{a+}^{\beta} \neq D_{a+}^{\alpha+\beta}$ in general.

Initial Conditions

Fractional derivatives require non-standard initial conditions. For the Caputo derivative of order $\alpha \in (n-1,n)$:

$${}^{C}D_{a+}^{\alpha}f(t)|_{t=a}=f^{(n)}(a),$$

whereas for the Riemann-Liouville derivative:

$$D_{a+}^{\alpha}f(t)|_{t=a}\neq f^{(n)}(a),$$

which highlights the difference in handling initial conditions in fractional calculus.

Remark 4. The choice between Caputo and Riemann-Liouville derivatives often depends on the physical context and the type of initial conditions available.

PHYSICAL MODELS INVOLVING FRACTIONAL CALCULUS OPERATORS

In this section, we explore various physical models that involve different fractional calculus operators. Each model is accompanied by the necessary mathematical expressions, followed by theorems, lemmas, corollaries, or remarks that highlight important properties and implications.

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Riemann-Liouville Fractional Integral and Derivative

Physical Model: Anomalous Diffusion

Anomalous diffusion, characterized by non-linear mean square displacement, can be modeled using the Riemann-Liouville fractional derivative. The fractional diffusion equation is given by:

$$\frac{\partial^{\alpha} u(x,t)}{\partial t^{\alpha}} = D_{\alpha} \frac{\partial^{2} u(x,t)}{\partial x^{2}}, \quad 0 < \alpha \leq 1,$$

where u(x,t) is the concentration of the diffusing substance, D_{α} is the generalized diffusion coefficient, and the fractional derivative is in the sense of Riemann-Liouville.

Theorem 5. The solution to the fractional diffusion equation for an initially localized distribution can be expressed as: $u(x,t) = \frac{1}{\sqrt{4D_{\alpha}t^{\alpha}}} \exp\left(-\frac{x^2}{4D_{\alpha}t^{\alpha}}\right)$.

Remark 5. For $\alpha = 1$, the equation reduces to the classical diffusion equation, and the solution represents a Gaussian distribution. When $0 < \alpha < 1$, the solution describes subdiffusion, indicating slower spreading of the substance.

Riemann-Liouville Fractional Integral in Relaxation Processes

The Riemann-Liouville fractional integral is used to model relaxation processes in viscoelastic materials. The stress-strain relationship can be written as:

$$\sigma(t) = E I_{0+}^{1-\alpha} \frac{d^{\alpha} \epsilon(t)}{dt^{\alpha}},$$

where $\sigma(t)$ is the stress, $\epsilon(t)$ is the strain, E is the modulus of elasticity, and $I_{0+}^{1-\alpha}$ is the Riemann-Liouville fractional integral.

Lemma 6. The creep compliance J(t), which characterizes the material's time-dependent deformation under a constant load, is given by: $J(t) = \frac{t^{\alpha}}{\Gamma(1+\alpha)}$.

Corollary 7. For $\alpha = 1$, the creep compliance becomes linear in time, which corresponds to classical linear viscoelastic behavior.

CAPUTO FRACTIONAL DERIVATIVE

Physical Model: Fractional Damped Oscillator

The Caputo fractional derivative is often used in modeling systems with memory effects, such as the fractional damped oscillator, described by:

$$\frac{d^2x(t)}{dt^2} + 2\gamma^C D_{0+}^{\alpha}x(t) + \omega_0^2 x(t) = 0,$$

where x(t) is the displacement, γ is the damping coefficient, ω_0 is the natural frequency, and ${}^CD_{0+}^{\alpha}$ is the Caputo fractional derivative.

Theorem 8. The solution for the fractional damped oscillator is given by: $x(t) = E_{\alpha}(-\gamma t^{\alpha})\cos(\omega_0 t)$,

where $E_{\alpha}(z)$ is the Mittag-Leffler function.

Remark 6. The use of the Caputo derivative allows the initial conditions to be specified in the same way as for the classical oscillator, making it a preferred choice for physical models.

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Caputo Fractional Derivative in Viscoelasticity

In the study of viscoelastic materials, the Caputo fractional derivative is used to model stress-strain relationships with memory. The constitutive equation is:

$$\sigma(t) = E_0 \epsilon(t) + E_1^{\ c} D_{0+}^{\alpha} \epsilon(t),$$

where E_0 and E_1 are material constants.

Lemma 9. The relaxation modulus G(t), which describes how the material relaxes under a constant strain, is given by: $G(t) = E_0 + \frac{E_1}{\Gamma(1-\alpha)} t^{-\alpha}$.

Corollary 10. When $\alpha = 1$, the model reduces to a standard linear viscoelastic model with exponential relaxation.

Grünwald-Letnikov Fractional Derivative

Physical Model: Fractional Difference Equations

The Grünwald-Letnikov derivative is useful in discretizing fractional differential equations for numerical simulations. A physical model governed by a fractional difference equation can be written as:

$$\Delta^{\alpha} y_n = \sum_{k=0}^n (-1)^k {\alpha \choose k} y_{n-k},$$

where Δ^{α} represents the fractional difference operator and y_n is the sequence representing the system's state at discrete time steps.

Theorem 11. The discrete solution y_n for a fractional difference equation with constant coefficients can be expressed as: $y_n = \sum_{k=0}^n \binom{n}{k} (-1)^k \lambda^{\alpha k} y_0$, where λ is a constant related to the system's properties.

Remark 7. This approach provides a practical way to implement fractional calculus in computational models, particularly in signal processing and control systems.

Hadamard Fractional Integral and Derivative

Physical Model: Scale-Invariant Systems

The Hadamard fractional derivative is particularly suited for systems with scale invariance, where the relevant dynamics depend on logarithmic time scales. The model can be expressed as:

$$\frac{d}{dt}\left(\frac{\partial^{\alpha}u(t)}{\partial(\ln t)^{\alpha}}\right) + au(t) = 0,$$

where u(t) is the state variable, and a is a constant.

Theorem 12. The solution to the scale-invariant fractional differential equation is: $u(t) = t^{-a}E_{\alpha}(-a(\ln t)^{\alpha})$,

where $E_{\alpha}(z)$ is the Mittag-Leffler function.

Remark 8. The Hadamard derivative is particularly useful in modeling phenomena where the system's response is sensitive to the rate of change on a logarithmic scale, such as in some biological systems and financial models.

Hadamard Fractional Integral in Thermodynamics

In thermodynamics, the Hadamard fractional integral is used to describe processes with memory and non-local effects. The internal energy U(t) of a system can be modeled as:

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$$U(t) = U_0 + I_{0+}^{\alpha} \left(\frac{dQ(t)}{dt} \right),$$

where Q(t) is the heat added to the system, and I_{0+}^{α} is the Hadamard fractional integral.

Lemma 13. The entropy S(t), related to the internal energy, can be expressed as: $S(t) = S_0 + \frac{1}{T} I_{0+}^{\alpha} \left(\frac{dQ(t)}{dt} \right)$,

•

where T is the temperature.

Corollary 14. For $\alpha = 1$, the expression reduces to the classical thermodynamic relation $S(t) = S_0 + \frac{1}{\tau}Q(t)$.

Erdélyi-Kober Fractional Integral and Derivative

Physical Model: Fractional Potential Fields

The Erdélyi-Kober fractional integral is applicable in potential theory, where it models fields influenced by fractional geometry. The potential $\Phi(x,t)$ can be written as:

$$\Phi(x,t) = I_{0+}^{\alpha,\beta} \rho(x,t),$$

where $\rho(x,t)$ is the source distribution, and $I_{0+}^{\alpha,\beta}$ is the Erdélyi-Kober fractional integral.

Theorem 15. The potential generated by a point source in a fractional medium is: $\Phi(r) = \frac{1}{r^{n-\alpha}} E_{\alpha,\beta} \left(-\frac{r^{\alpha}}{\Gamma(\beta)} \right)$,

where r is the distance from the source, and $E_{\alpha,\beta}(z)$ is the generalized Mittag-Leffler function.

Remark 9. The Erdélyi-Kober integral allows for the modeling of potentials in media with fractional dimensionality, which is useful in certain geophysical and electrostatic applications.

Erdélyi-Kober Fractional Derivative in Fluid Dynamics

In fluid dynamics, the Erdélyi-Kober fractional derivative can be used to model anomalous diffusion in porous media. The velocity field v(x,t) satisfies the fractional Navier-Stokes equation:

$$\frac{\partial^{\alpha} v(x,t)}{\partial t^{\alpha}} + (v \cdot \nabla)v = -\nabla p + \nu I_{0+}^{\beta} \nabla^{2} v,$$

where p is the pressure, ν is the kinematic viscosity, and I_{0+}^{β} is the Erdélyi-Kober fractional derivative.

Lemma 16. The flow profile in a cylindrical pipe for a fractional fluid is given by: $v(r,t) = \frac{1}{r^{1-\beta}} E_{\alpha,\beta} \left(-\frac{r^{\alpha}}{\Gamma(\beta)} t^{\alpha} \right)$.

Corollary 17. When $\alpha = \beta = 1$, the expression reduces to the classical Hagen-Poiseuille flow profile.

Miller-Ross Fractional Operator

Physical Model: Sequential Fractional Differential Equations

The Miller-Ross fractional operator is particularly useful in solving sequential fractional differential equations. Consider a model governed by a sequential fractional differential equation:

$$D_t^{\alpha}D_t^{\beta}u(t)=\lambda u(t),$$

where D_t^{α} and D_t^{β} are fractional derivatives of orders α and β , respectively.

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Theorem 18. The solution to the sequential fractional differential equation is given by: $u(t) = E_{\alpha,\beta}(\lambda t^{\alpha+\beta})$, where $E_{\alpha,\beta}(z)$ is the two-parameter Mittag-Leffler function.

Remark 10. The Miller-Ross operator is particularly effective in models where the dynamics involve multiple fractional orders, such as in complex viscoelastic materials and anomalous transport processes.

Weyl Fractional Integral and Derivative

Physical Model: Fractional Fourier Transform

The Weyl fractional derivative is closely related to the Fourier transform and is used in signal processing and quantum mechanics. The fractional Fourier transform (FrFT) is defined as:

$$\mathcal{F}^{\alpha}[f(x)](\omega) = \int_{-\infty}^{\infty} f(x)e^{-i\omega x}D_{-\infty}^{\alpha}e^{i\omega x}dx,$$

where $D_{-\infty}^{\alpha}$ is the Weyl fractional derivative.

Theorem 19. The fractional Fourier transform of a Gaussian function $f(x) = e^{-ax^2}$ is given by: $\mathcal{F}^{\alpha}[f(x)](\omega) = \sqrt{\frac{\pi}{a}}e^{-\frac{\omega^2}{4a}-i\alpha\omega^2}$.

Remark 11. The Weyl fractional derivative is essential in fractional calculus, particularly in problems involving infinite domains and frequency-based analysis.

Marchaud Fractional Derivative

Physical Model: Fractional Population Dynamics

The Marchaud fractional derivative generalizes the Riemann-Liouville derivative and is used in models of population dynamics with memory effects. The population dynamics equation is:

$$\frac{d^{\alpha}N(t)}{dt^{\alpha}} = rN(t)\left(1 - \frac{N(t)}{K}\right) - D_{-\infty}^{\alpha}N(t),$$

where N(t) is the population at time t, r is the growth rate, and K is the carrying capacity.

Lemma 20. The steady-state solution for the fractional logistic equation is given by: $N(t) = K \left(1 - \frac{e^{rt}}{1 + e^{rt}}\right)^{\alpha}$.

Corollary 21. For $\alpha = 1$, the solution reduces to the classical logistic model, describing the standard population growth.

Prabhakar Fractional Operator

Physical Model: Generalized Viscoelastic Models

The Prabhakar fractional operator, which involves a three-parameter Mittag-Leffler function, is applied in generalized viscoelastic models. The stress-strain relationship is:

$$\sigma(t) = E D_{0+}^{\alpha,\beta,\gamma} \epsilon(t),$$

where $D_{0+}^{\alpha,\beta,\gamma}$ is the Prabhakar fractional derivative, and E is the modulus of elasticity.

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Theorem 22. The creep compliance J(t) for the Prabhakar model is given by: $J(t) = \frac{1}{E} E_{\alpha,\beta}^{\gamma}(\lambda t^{\alpha})$, where $E_{\alpha,\beta}^{\gamma}(z)$ is the three-parameter Mittag-Leffler function.

Remark 12. The Prabhakar operator generalizes various models of viscoelasticity and is useful in describing complex materials with non-linear memory effects.

Jumarie Fractional Derivative

Physical Model: Fractional Option Pricing

The Jumarie fractional derivative is used in financial mathematics, particularly in modeling option pricing under anomalous diffusion. The fractional Black-Scholes equation is:

$$\frac{\partial C}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 C}{\partial S^2} + rS \frac{\partial C}{\partial S} - rC = \frac{\partial^\alpha C}{\partial t^\alpha},$$

where C(S, t) is the option price, S is the asset price, r is the risk-free rate, and σ is the volatility.

Lemma 23. The solution to the fractional Black-Scholes equation for a European call option is: $C(S,t) = SN(d_1) - Ke^{-r(T-t)}N(d_2)$, where d_1 and d_2 are modified to account for the fractional time derivative.

Corollary 24. For $\alpha = 1$, the solution reduces to the classical Black-Scholes formula.

Kilbas-Saigo Fractional Operators

Physical Model: Anomalous Transport in Porous Media

Kilbas-Saigo fractional operators generalize the Erdélyi-Kober integrals and are used to model anomalous transport in porous media. The transport equation is:

$$\frac{\partial^{\alpha,\beta}u(x,t)}{\partial t^{\alpha,\beta}} + v \frac{\partial u(x,t)}{\partial x} = D_{\alpha,\beta} \frac{\partial^2 u(x,t)}{\partial x^2},$$

where $D_{\alpha,\beta}$ is the Kilbas-Saigo fractional derivative.

Theorem 25. The concentration profile u(x,t) for the transport equation in porous media is given by: $u(x,t) = \frac{1}{\sqrt{4\pi D_{\alpha,\beta}t^{\alpha}}} e^{-\frac{(x-vt)^2}{4D_{\alpha,\beta}t^{\alpha}}}$.

Remark 13. The Kilbas-Saigo operators are versatile tools in modeling transport phenomena with fractional-order dynamics and memory effects.

Conformable Fractional Derivative

Physical Model: Fractional Harmonic Oscillator

The conformable fractional derivative is a more recent operator that is easier to interpret and apply. Consider a fractional harmonic oscillator:

$$\frac{d^2x(t)}{dt^2} + \omega^2x(t) = -\gamma T_\alpha \frac{dx(t)}{dt},$$

where T_{α} is the conformable fractional derivative, and γ is the damping coefficient.

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Lemma 26. The solution to the fractional harmonic oscillator equation is: $x(t) = Ae^{-\gamma t^{\alpha}}\cos(\omega t)$, where A is the amplitude, and ω is the angular frequency.

Corollary 27. For $\alpha = 1$, the solution reduces to the classical damped harmonic oscillator.

Atangana-Baleanu Fractional Derivative

Physical Model: Fractional Heat Conduction

The Atangana-Baleanu fractional derivative, with its non-local and non-singular kernel, is used in modeling heat conduction in heterogeneous materials. The fractional heat conduction equation is:

$$^{AB}D_t^{\alpha}u(x,t) = k\frac{\partial^2 u(x,t)}{\partial x^2},$$

where ${}^{AB}D_t^{\alpha}$ is the Atangana-Baleanu fractional derivative, and k is the thermal conductivity.

Theorem 28. The temperature distribution u(x,t) in a rod is given by: $u(x,t) = \frac{1}{\sqrt{4\pi k t^{\alpha}}} e^{-\frac{x^2}{4kt^{\alpha}}}$, where the fractional order α affects the rate of heat diffusion.

Remark 14. The Atangana-Baleanu derivative is effective in modeling complex thermal processes with non-local memory effects.

Mittag-Leffler Fractional Operators

Physical Model: Anomalous Relaxation Processes

Mittag-Leffler fractional operators generalize the fractional derivatives and are used in modeling anomalous relaxation processes. The relaxation equation is:

$$\frac{d^{\alpha}R(t)}{dt^{\alpha}} + \lambda R(t) = 0,$$

where λ is a relaxation constant.

Theorem 29. The solution to the anomalous relaxation equation is: $R(t) = E_{\alpha}(-\lambda t^{\alpha})$, where $E_{\alpha}(z)$ is the Mittag-Leffler function.

Remark 15. The Mittag-Leffler operators provide a robust framework for describing a wide range of anomalous processes in physics and engineering.

Saigo Fractional Operators

Physical Model: Fractional Diffusion in Complex Media

Saigo fractional operators extend the Riemann-Liouville and Erdélyi-Kober integrals and are used to model diffusion in complex media. The fractional diffusion equation is:

$$\frac{\partial^{\alpha,\beta}u(x,t)}{\partial t^{\alpha,\beta}} = D\nabla^2 u(x,t),$$

where $\partial^{\alpha,\beta}/\partial t^{\alpha,\beta}$ is the Saigo fractional derivative.

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Theorem 30. The solution for the diffusion equation in complex media is: $u(x,t) = \frac{1}{\sqrt{4\pi D t^{\alpha}}} e^{-\frac{x^2}{4D t^{\alpha}}}$, where the parameters α and β control the diffusion process.

Remark 16. Saigo fractional operators are particularly useful in describing diffusion processes with non-standard geometries and boundary conditions.

Hilfer Fractional Derivative

Physical Model: Anomalous Diffusion

The Hilfer fractional derivative interpolates between the Riemann-Liouville and Caputo derivatives and is used in models of anomalous diffusion. The fractional diffusion equation is:

$$D_t^{\alpha,\beta}u(x,t) = D\frac{\partial^2 u(x,t)}{\partial x^2},$$

where $D_t^{\alpha,\beta}$ is the Hilfer fractional derivative.

Lemma 31. The solution to the Hilfer fractional diffusion equation is: $u(x,t) = \frac{1}{\sqrt{4\pi Dt^{\alpha}}} e^{-\frac{x^2}{4Dt^{\alpha}}}$, where the parameters α and β determine the type of anomalous diffusion.

Corollary 32. For $\alpha = 1$ and $\beta = 0$, the equation reduces to the classical diffusion equation.

ADVANCED FRACTIONAL MODELS

Riesz Fractional Derivative

Physical Model: Fractional Wave Equation

The Riesz fractional derivative is a multidimensional generalization of the Riemann-Liouville derivative, often used in fractional partial differential equations. The fractional wave equation in n dimensions is given by:

$$\frac{\partial^2 u(x,t)}{\partial t^2} = -c^2(-\Delta)^{\alpha/2}u(x,t),$$

where Δ is the Laplace operator and α is the order of the fractional derivative.

Theorem 33. The solution to the fractional wave equation using the Riesz fractional derivative is: $u(x,t) = \int_{\mathbb{R}^n} G(x-y,t)u(y,0) \, dy$, where G(x,t) is the Green's function associated with the fractional wave operator.

Remark 17. The Riesz fractional derivative captures the spatial dispersion effects in wave propagation, making it suitable for modeling phenomena in complex media.

Riesz-Caputo Fractional Derivative

Physical Model: Fractional Diffusion with Memory Effects

The Riesz-Caputo fractional derivative modifies the Riesz fractional derivative to incorporate initial conditions similar to the Caputo derivative. It is used in models where non-integer order dynamics play a significant role. The fractional diffusion equation is:

$$\frac{\partial^{\alpha} u(x,t)}{\partial t^{\alpha}} = -D(-\Delta)^{\beta/2} u(x,t),$$

where α and β are fractional orders.

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Lemma 34. The solution to the Riesz-Caputo fractional diffusion equation is: $u(x,t) = \int_{\mathbb{R}^n} H(x-y,t^{\alpha})u(y,0) dy$, where H(x,t) is the corresponding Green's function.

Corollary 35. For $\alpha = 1$ and $\beta = 2$, the equation reduces to the classical diffusion equation.

Kober Fractional Operator

Physical Model: Hypergeometric Function Integrals

The Kober fractional operator generalizes the Erdélyi-Kober operator and is used in problems involving special functions, particularly hypergeometric functions. The operator is defined by:

$$(K_{\alpha,\beta}f)(x) = x^{-\alpha} \int_0^x (x-t)^{\alpha-1} t^{\beta-1} f(t) dt.$$

Theorem 36. For certain classes of functions f, the Kober fractional operator transforms hypergeometric functions as: $(K_{\alpha,\beta}f)(x) = x^{\gamma}{}_{2}F_{1}(\alpha,b;c;x)$, where ${}_{2}F_{1}(\alpha,b;c;x)$ is the hypergeometric function.

Remark 18. The Kober operator is particularly useful in mathematical physics for solving integrals involving special functions.

Fourier Fractional Derivative

Physical Model: Fractional Signal Processing

The Fourier fractional derivative is defined in the frequency domain and is widely used in signal processing and wave propagation. The Fourier fractional derivative of a function f(x) is given by:

$$F[D^{\alpha}f(x)](k) = |k|^{\alpha}F[f(x)](k),$$

where F denotes the Fourier transform.

Theorem 37. In the context of signal processing, the Fourier fractional derivative modifies the signal's spectrum as: $f_{\alpha}(x) = F^{-1}[|k|^{\alpha}F[f(x)](k)]$, where F^{-1} is the inverse Fourier transform.

Remark 19. The Fourier fractional derivative allows for precise control over the frequency components of a signal, making it effective in filtering and signal analysis.

Katugampola Fractional Integral and Derivative

Physical Model: Generalized Fractional Dynamics

The Katugampola fractional operator unifies several types of fractional integrals and derivatives, including Riemann-Liouville and Hadamard types. It is defined by:

$$(K_{a+}^{\alpha,\beta}f)(x) = \frac{1}{\Gamma(\beta)} \int_{a}^{x} \left(\frac{x^{\alpha} - t^{\alpha}}{\alpha}\right)^{\beta - 1} f(t) dt,$$

where $\alpha > 0$ and $\beta > 0$.

Lemma 38. The Katugampola fractional derivative generalizes the classical derivative as: $D_{a+}^{\alpha,\beta}f(x) = \frac{d}{dx}(K_{a+}^{\alpha,\beta}f)(x)$, which reduces to the Riemann-Liouville derivative when $\alpha = 1$.

Remark 20. This operator is particularly useful in mathematical physics for modeling generalized fractional dynamics in various physical systems.

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Cresson Derivative

Physical Model: Fractional Dynamics in Chaotic Systems

The Cresson derivative extends fractional calculus within the framework of non-standard analysis, making it useful in modeling fractal and chaotic systems. It is defined as:

$$\frac{d^{\alpha}f(x)}{dx^{\alpha}} = \lim_{\epsilon \to 0} \frac{f(x + \epsilon^{\alpha}) - f(x)}{\epsilon^{\alpha}}.$$

Theorem 39. In chaotic systems, the Cresson derivative models the fractional dynamics as: $\frac{d^{\alpha}x(t)}{dt^{\alpha}} = f(x(t))$, where f(x) represents the chaotic dynamics.

Remark 21. The Cresson derivative provides a new perspective on fractional derivatives, particularly in systems with fractal or chaotic behavior.

Chung-Taylor Fractional Operator

Physical Model: Fractional Brownian Motion

The Chung-Taylor fractional operator is used in stochastic processes and fractional Brownian motion, which models random phenomena in fractional contexts. The operator is defined by:

$$C_t^{\alpha} f(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t (t-\tau)^{-\alpha} f(\tau) d\tau,$$

where $0 < \alpha < 1$.

Lemma 40. The Chung-Taylor operator models fractional Brownian motion as: $B_H(t) = C_t^H W(t)$, where $B_H(t)$ is the fractional Brownian motion and W(t) is the standard Wiener process.

Corollary 41. For H = 1/2, the fractional Brownian motion reduces to standard Brownian motion.

Gerasimov-Caputo Fractional Operator

Physical Model: Viscoelastic Materials

The Gerasimov-Caputo fractional operator is a modification of the Caputo derivative and is used in models of viscoelasticity and materials with hereditary properties. The fractional viscoelastic model is given by:

$$\sigma(t) = E_0 \epsilon(t) + E_1 \frac{d^{\alpha} \epsilon(t)}{dt^{\alpha}},$$

where $\sigma(t)$ is the stress, $\epsilon(t)$ is the strain, and E_0 , E_1 are material constants.

Theorem 42. The solution to the viscoelastic model using the Gerasimov-Caputo derivative is: $\epsilon(t) = \frac{1}{E_0} \left(\sigma(t) - E_1 \frac{d^{\alpha} \sigma(t)}{dt^{\alpha}} \right)$.

Remark 22. The Gerasimov-Caputo operator effectively models materials with memory effects, capturing the hereditary nature of viscoelasticity.

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Multivariable Fractional Derivatives

Physical Model: Higher-Dimensional Systems

Multivariable fractional derivatives extend fractional calculus to functions of multiple variables. These are useful in modeling higher-dimensional systems and fractional partial differential equations. For a function $f(x_1, x_2, ..., x_n)$, the multivariable fractional derivative is defined as:

$$D^{\alpha}f(x) = \frac{\partial^{\lfloor \alpha \rfloor}}{\partial x^{\lfloor \alpha \rfloor}} \int_{\mathbb{R}^n} \frac{f(y)}{|x - y|^{n + \alpha}} \, dy,$$

where $[\alpha]$ denotes the integer part of α .

Theorem 43. For a multivariable power function $f(x) = \prod_{i=1}^n x_i^{p_i}$, the multivariable fractional derivative is: $D^{\alpha} \prod_{i=1}^n x_i^{p_i} = \prod_{i=1}^n \frac{\Gamma(p_i+1)}{\Gamma(p_i+\alpha+1)} x_i^{p_i+\alpha}$.

Remark 23. Multivariable fractional derivatives are essential in modeling complex systems in higher dimensions, such as those found in fluid dynamics and multi-dimensional diffusion processes.

Vector Fractional Operators

Physical Model: Fluid Dynamics and Electromagnetism

Vector fractional operators generalize fractional derivatives to vector fields and are used in fluid dynamics and electromagnetism. For a vector field $\mathbf{F}(x)$, the vector fractional derivative is defined as:

$$D^{\alpha}\mathbf{F}(x) = -(-\Delta)^{\alpha/2}\mathbf{F}(x),$$

where $-\Delta$ is the vector Laplacian.

Theorem 44. For a vector field $\mathbf{F}(x) = \nabla \phi(x)$, where $\phi(x)$ is a scalar potential, the vector fractional derivative is: $D^{\alpha} \nabla \phi(x) = \nabla [-(-\Delta)^{\alpha/2} \phi(x)]$.

Remark 24. Vector fractional operators are crucial for modeling vector fields in electromagnetism and fluid dynamics, where fractional differential equations govern the behavior of fields.

Non-singular Kernel Fractional Derivatives

Physical Model: Avoiding Singularities in Fractional Models

Non-singular kernel fractional derivatives, such as the Atangana-Baleanu derivative, avoid singularities in the kernel, making them suitable for physical and engineering applications. The Atangana-Baleanu fractional derivative is defined as:

$$D_{a+}^{\alpha}f(t) = \frac{1}{\Gamma(\alpha)} \int_{a}^{t} (t-\tau)^{\alpha-1} e^{-\lambda(t-\tau)} f(\tau) d\tau.$$

Theorem 45. The Atangana-Baleanu fractional derivative of the exponential function $f(t) = e^{-t}$ is: $D_{a+}^{\alpha} e^{-t} = \frac{\Gamma(1+\alpha)}{(\lambda+1)^{\alpha}} e^{-t}$.

Remark 25. Non-singular kernel fractional derivatives are beneficial in applications where singular behavior of the kernel is undesirable, such as in modeling complex viscoelastic and biological systems.

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Memory-dependent Fractional Operators

Physical Model: Processes with Past Influence

Memory-dependent fractional operators incorporate memory kernels, allowing the modeling of processes where past states influence the present. For a memory-dependent operator, we have:

$$D_{a+}^{\alpha}f(t)=\int_{a}^{t}\frac{f(\tau)}{(t-\tau)^{\alpha}}\phi(t-\tau)\,d\tau,$$

where $\phi(t-\tau)$ is a memory kernel.

Theorem 46. For a linear memory kernel $\phi(t-\tau) = e^{-\beta(t-\tau)}$, the memory-dependent fractional derivative is: $D_{a+}^{\alpha}e^{-\beta t} = \frac{\Gamma(1+\alpha)}{(\beta+1)^{\alpha}}e^{-\beta t}$.

Remark 26. Memory-dependent fractional operators are applicable in modeling processes with memory effects, such as viscoelastic materials and biological systems with long-term dependencies.

Stieltjes Fractional Integral

Physical Model: Stochastic Processes and Irregular Systems

The Stieltjes fractional integral extends the Stieltjes integral to fractional orders and is useful in stochastic processes. For a function f(t), the Stieltjes fractional integral is defined as:

$$I_{a+}^{\alpha}f(t) = \frac{1}{\Gamma(\alpha)} \int_{a}^{t} (t-\tau)^{\alpha-1} f(\tau) d\tau.$$

Theorem 47. For a Brownian motion B(t), the Stieltjes fractional integral is: $I_{0+}^{\alpha}B(t) = \frac{1}{\Gamma(\alpha)}\int_{0}^{t}(t-\tau)^{\alpha-1}B(\tau)\,d\tau$.

Remark 27. The Stieltjes fractional integral is applicable in modeling stochastic processes with irregular behavior, such as fractional Brownian motion.

Fractional Variational Operators

Physical Model: Mechanics and Optimization

Fractional variational operators extend variational calculus to fractional orders and are used in mechanics and optimization. For a functional J[f] defined by:

$$J[f] = \int_{a}^{b} L(t, f(t), D^{\alpha}f(t)) dt,$$

where D^{α} denotes the fractional derivative.

Theorem 48. The Euler-Lagrange equation for a fractional variational problem is: $\frac{\partial L}{\partial f} - \frac{d}{dt} \left(\frac{\partial L}{\partial (D^{\alpha} f)} \right) = 0$.

Remark 28. Fractional variational calculus provides tools for solving optimization problems and modeling physical systems with fractional-order dynamics.

p-adic Fractional Operators

Physical Model: p-adic Analysis and Quantum Calculus

p-adic fractional operators are defined in the context of p-adic analysis and are relevant in number theory and physics. For a p-adic function f(x), the p-adic fractional operator is defined as:

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$$D_p^{\alpha}f(x) = \frac{1}{\Gamma(\alpha)} \int_0^x (x-\tau)^{\alpha-1} f(\tau) d\tau.$$

Theorem 49. For a p-adic power function $f(x) = x^p$, the p-adic fractional derivative is: $D_p^{\alpha} x^p = \frac{\Gamma(p+1)}{\Gamma(p+\alpha+1)} x^{p+\alpha}$.

Remark 29. p-adic fractional operators are used in specialized areas such as quantum calculus and number theory, extending fractional calculus concepts to p-adic analysis.

Fractional Difference Operators

Physical Model: Discrete Systems and Time Series Analysis

Fractional difference operators are discrete analogs of fractional derivatives, used in numerical methods and time series analysis. For a discrete function f(k), the fractional difference operator is defined as:

$$\Delta_q^{\alpha} f(k) = \sum_{j=0}^k {\alpha \choose j} [f(k) - f(k-j)],$$

where Δ_a is the q-difference operator.

Theorem 50. For a discrete power function $f(k) = k^p$, the fractional difference operator is: $\Delta_q^{\alpha} k^p = \frac{\Gamma(p+1)}{\Gamma(p+\alpha+1)} k^{p+\alpha}$.

Remark 30. Fractional difference operators are important for modeling and analyzing discrete systems and time series data, providing tools for extending fractional calculus to discrete contexts.

Fractional Laplacian

Physical Model: Anomalous Diffusion

The fractional Laplacian is an extension of the Laplace operator to fractional orders, commonly used in the study of anomalous diffusion. It is defined as:

$$(-\Delta)^{\alpha/2}f(x) = C_{\alpha} \int_{\mathbb{D}^n} \frac{f(x) - f(y)}{|x - y|^{n+\alpha}} \, dy,$$

where C_{α} is a normalization constant.

Theorem 51. For a Gaussian function $f(x) = e^{\frac{|x|^2}{2\sigma^2}}$, the fractional Laplacian is: $(-\Delta)^{\alpha/2}e^{\frac{|x|^2}{2\sigma^2}} = \frac{2^{\alpha}\Gamma(\frac{n}{2}+\alpha)}{\pi^{n/2}\Gamma(\alpha)}(\frac{1}{\sigma^2})^{\alpha}e^{-\frac{|x|^2}{2\sigma^2}}$.

Remark 31. The fractional Laplacian is widely used in modeling anomalous diffusion and processes governed by Lévy flights or stable distributions.

Fractional Poisson Process

Physical Model: Waiting Times in Stochastic Processes

The fractional Poisson process generalizes the standard Poisson process to fractional orders, used for modeling waiting times and other stochastic phenomena. It is characterized by a waiting time distribution with fractional characteristics.

Theorem 53. The probability distribution of the waiting time in a fractional Poisson process is given by: $P(T > t) = e^{-\lambda t^{\alpha}}$,

where λ is the rate parameter and α is the fractional order.

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Corollary 52. The mean waiting time in a fractional Poisson process is: $\mathbb{E}[T] = \frac{1}{11/\alpha}$

Remark 32. The fractional Poisson process is useful in modeling stochastic systems with waiting times that exhibit fractional-order behavior, providing a more flexible framework compared to the classical Poisson process.

Variable-order Fractional Operators

Physical Model: Systems with Dynamically Changing Orders

Variable-order fractional operators allow the fractional order to vary with time or space, providing a more flexible modeling framework. For a variable-order fractional operator:

$$D_{a+}^{\alpha(t)}f(t) = \frac{d}{dt}I_{a+}^{\alpha(t)}f(t),$$

where $\alpha(t)$ is a function of time.

Theorem 54. For a time-dependent fractional derivative where $\alpha(t) = \frac{1}{2} + \frac{t}{2}$, the operator is: $D_{a+}^{\alpha(t)} f(t) = \frac{d}{dt} \left[\int_a^t (t-\tau)^{\alpha(t)-1} f(\tau) d\tau \right]$.

Remark 33. Variable-order fractional operators are useful in modeling systems where the fractional order changes dynamically, such as in adaptive control systems and time-varying processes.

Fractional q-Calculus Operators

Physical Model: Quantum Calculus and Special Functions

Fractional q-calculus operators extend classical q-calculus to fractional orders, relevant in quantum calculus and special functions. For a function f(x), the fractional q-derivative is defined as:

$$D_q^{\alpha} f(x) = \frac{1}{\Gamma_q(\alpha)} \int_0^x (x - \tau)_q^{\alpha - 1} f(\tau) d\tau,$$

where D_q^{α} is the q-difference operator.

Theorem 55. For a q-power function $f(x) = x^p$, the fractional q-derivative is: $D_q^{\alpha} x^p = \frac{\Gamma_q(p+1)}{\Gamma_q(p+\alpha+1)} x^{p+\alpha}$.

Remark 34. Fractional q-calculus operators are used in quantum calculus and special functions, extending the principles of fractional calculus to the q-calculus framework.

Generalized Fractional Operators

Physical Model: Tailored Applications in Various Fields

Generalized fractional operators include various modifications of classical fractional operators, allowing for tailored applications in specific fields. For a generalized fractional operator, the definition is:

$$D_{a+}^{\alpha}f(t) = \frac{1}{\Gamma(\alpha)} \int_{a}^{t} (t-\tau)^{\alpha-1} \phi(t-\tau)f(\tau) d\tau,$$

where $\phi(t-\tau)$ is a general kernel function.

Theorem 56. For a specific kernel $\phi(t-\tau) = e^{-\beta(t-\tau)}$, the generalized fractional operator is: $D_{a+}^{\alpha}e^{-\beta t} = \frac{\Gamma(1+\alpha)}{(\beta+1)^{\alpha}}e^{-\beta t}$.

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Remark 35. Generalized fractional operators provide flexibility in modeling diverse applications in fields such as economics, biology, and engineering, by tailoring the operators to specific needs and conditions.

Applications in Specific Fields

Physics

Anomalous Diffusion

Fractional calculus is used to model anomalous diffusion, where particles spread in a manner that deviates from classical Brownian motion. The fractional diffusion equation is given by:

$$\frac{\partial^{\alpha} u(x,t)}{\partial t^{\alpha}} = D_0 \frac{\partial^{\beta} u(x,t)}{\partial x^{\beta}},$$

where $0 < \alpha < 1$ denotes the order of the time derivative and $0 < \beta < 2$ denotes the order of the spatial derivative.

Theorem 57. The solution to the fractional diffusion equation for an initial condition $u(x, 0) = \delta(x)$ (a Dirac delta function) is:

$$u(x,t) = \frac{1}{\Gamma(\alpha)(2D_0t)^{\alpha}} \int_{-\infty}^{\infty} e^{-\frac{x^2}{4D_0t}} dx.$$

Remark 36. This solution represents a Gaussian profile with a variance that grows sublinearly with time, indicating slower spreading compared to classical diffusion.

Electromagnetism

Fractional calculus can be applied to Maxwell's equations to model anomalous electromagnetic wave propagation. For a fractional-order Maxwell's equation:

$$\frac{\partial^{\alpha} \mathbf{E}(x,t)}{\partial t^{\alpha}} - c^{2} \nabla \times \mathbf{B}(x,t) = \mathbf{0},$$

where α is the fractional order of time derivative and **E** and **B** are the electric and magnetic fields.

Theorem 58. For a plane wave solution, the fractional Maxwell's equation can be written as:

$$\mathbf{E}(x,t) = \mathbf{E}_0 e^{i(\omega t - kx)},$$

where the wave frequency ω and wave number k satisfy:

$$\omega^{\alpha}=c^2k^{\alpha}.$$

Remark 37. The fractional order affects the dispersion relation, leading to non-standard wave propagation characteristics.

Engineering

Control Systems

Fractional-order controllers provide more flexible tuning for control systems. The fractional PI controller is defined as:

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$$C(s) = K_p + \frac{K_i}{s^{\alpha'}}$$

where K_p is the proportional gain, K_i is the integral gain, and α is the fractional order.

Theorem 59. For a plant transfer function $G(s) = \frac{1}{s^2+1}$, the closed-loop transfer function with a fractional PI controller is:

$$T(s) = \frac{G(s)C(s)}{1 + G(s)C(s)} = \frac{K_p + \frac{K_i}{s^{\alpha}}}{s^2 + 1 + K_p + \frac{K_i}{s^{\alpha}}}.$$

Remark 38. Fractional PI controllers can improve system performance and stability, particularly in systems with complex dynamics.

Viscoelastic Materials

Fractional calculus models the stress-strain relationship in viscoelastic materials. The fractional viscoelastic model is given by:

$$\sigma(t) = E_0 \varepsilon(t) + \eta \frac{\partial^{\alpha} \varepsilon(t)}{\partial t^{\alpha}},$$

where $\sigma(t)$ is the stress, $\varepsilon(t)$ is the strain, E_0 is the Young's modulus, and η is the viscosity.

Theorem 60. For a step input strain $\varepsilon(t) = \varepsilon_0 H(t)$, the stress response is:

$$\sigma(t) = E_0 \varepsilon_0 + \eta \frac{\varepsilon_0}{\Gamma(1-\alpha)} t^{\alpha-1}.$$

Remark 39. The fractional derivative in the stress-strain relationship models the delayed response typical in viscoelastic materials.

Biology

Population Dynamics

Fractional differential equations model biological populations with memory effects. The fractional population model is:

$$\frac{\partial^{\alpha} N(t)}{\partial t^{\alpha}} = rN(t) \left(1 - \frac{N(t)}{K} \right),$$

where N(t) is the population size, r is the growth rate, and K is the carrying capacity.

Theorem 61. For an initial condition $N(0) = N_0$, the solution to the fractional logistic equation is:

$$N(t) = \frac{KN_0}{N_0 + (K - N_0)e^{-rt^{\alpha}}}.$$

Remark 40. The fractional order α affects the growth rate and time to reach equilibrium, modeling populations with non-exponential growth characteristics.

Epidemiology

Fractional calculus models the spread of diseases in populations with memory effects. The fractional SIR model is:

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$$\frac{\partial^{\alpha} S(t)}{\partial t^{\alpha}} = -\beta S(t)I(t),$$

$$\frac{\partial^{\alpha} I(t)}{\partial t^{\alpha}} = \beta S(t)I(t) - \gamma I(t),$$

$$\frac{\partial^{\alpha} R(t)}{\partial t^{\alpha}} = \gamma I(t),$$

where S(t), I(t), and R(t) are the susceptible, infected, and recovered populations, respectively, and β and γ are the transmission and recovery rates.

Theorem 62. The solution for S(t) in terms of I(t) is:

$$S(t) = S_0 - \frac{\beta}{\gamma} \int_0^t I(\tau) d\tau.$$

Remark 41. The fractional derivative models the spread of infectious diseases with memory effects, capturing the complex dynamics of disease propagation.

Economics

Financial Modeling

Fractional Brownian motion models asset prices in financial markets. The fractional Black-Scholes model for option pricing is:

$$dS(t) = \mu S(t) dt + \sigma S(t) dW_H(t)$$

where $W_H(t)$ is the fractional Brownian motion with Hurst parameter H.

Theorem 63. The option price under the fractional Black-Scholes model is given by:

$$C(t) = e^{-r(T-t)} \mathbb{E}[\max(S(T) - K, 0)],$$

where r is the risk-free rate, K is the strike price, and T is the maturity time.

Remark 42. Fractional Brownian motion provides a more accurate representation of market volatility and price dynamics compared to classical Brownian motion.

Econometric Models

Fractional integration is used in econometrics to model long-memory processes. The fractional ARFIMA model is:

$$\Phi(B)(1-B)^dY_t = \Theta(B)\epsilon_t,$$

where B is the backshift operator, d is the fractional integration parameter, $\Phi(B)$ and $\Theta(B)$ are polynomials, and ϵ_t is white noise.

Theorem 64. For a stationary process, the autocorrelation function is:

$$\rho(h) \sim h^{2d-1},$$

where h is the lag.

Remark 43. Fractional ARFIMA models capture long-memory behavior in economic time series, providing better forecasts and understanding of economic dynamics.

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ENGINEERING AND CONTROL SYSTEMS

Fractional calculus has found applications in control systems, particularly in the design of fractional PID controllers. These controllers offer more flexibility and robustness compared to classical PID controllers.

Biology and Medicine

In biology, fractional models are used to describe anomalous diffusion in cells and tissues. The fractional diffusion equation is:

$$\frac{\partial^{\alpha} C(x,t)}{\partial t^{\alpha}} = D \frac{\partial^{2} C(x,t)}{\partial x^{2}}$$

where C(x, t) represents the concentration of a substance, and D is the diffusion coefficient.

Finance and Economics

Fractional calculus is applied in finance for modeling memory effects in market volatility. The fractional Black-Scholes model is one such application.

INTERPRETATION AND DISCUSSION

Versions of some fractional derivatives and the corresponding physical theories have been rigorously discussed in recent sections. This section provides interpretation of the findings from these models and their relevance to areas that may be pertinent in diverse fields.

Anomalous Diffusion

In this study we were able to demonstrate that anomalous diffusion can be modeled using fractional calculus. For example, the fractional algebra in diffusion equations by Riemann-Liouville and Caputo derivatives represent particles spread slower than intuitive view from CTRW. This is consistent with observations in the real world of subdiffusive phenomena, where mean squared displacement increases more slowly over time than linear. The interpretation is that fractional models are especially well-suited for describing the effects of complex medium on particle dynamics.

Electromagnetism

Fractional derivatives have been used to derive fractional Maxwell's equations, which present wave propagation in memory or non-local materials from a new perspective of view when considered within the realm of electromagnetic theory. Newly proposed dispersion relations, constructed from such Riesz and Weyl fractional operators provide insights into how or where to invoke there quantifications in order to ameliorate classical models for modeling both dispersive mechanisms along with attenuation processes which may be overlooked by the standard formulations thus providing a better understanding of wave signal propagation even within quite complex material media like metamaterials displaying anomalous dispensing properties.

Control Systems

Fractional calculus, in particular fractional PI (FPI) and Fractional PID controllers bring great benefits to control systems. The results show that the new fractional-order controllers offer more flexibility in adjusting system dynamics than traditional integer order systems, which helps improve its performance. Ability to model and compensate Non-integer order dynamics which ensures higher level of stability and robustness in complex control Autodesk. This is especially important in systems with time delays or non-linearities, which regular models may be hindered by.

Viscoelastic Materials

Modeling of a significant amount of materials (e.g., polymers) under stress require the utilization fractional derivatives to account for inherent visco-elasticity. The results obtained by the fractional calculus models demonstrate that more accurate time values can be found while modelling this delayed stress–strain response in comparison to classical

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forms. Modeling materials with complex time dependent symmetry breaking and heterogeneity is not feasible using traditional models, warranting a representation that respects the underlying physics.

Population Dynamics

The fractional calculus model is commonly employed in population dynamics, such as the well–known application to a fraction logistic growth model which more accurate predictions of biological phenomena are realized when memory effects are considered. In Fig 4C–F, all fractional models display distinct deviations from classical exponential growth as a consequence of the convolution with past states affecting its current dynamics. This approach gives us a clear insight of when and why the population trends concerning historical effects are going to dominate future growth rates in lotic ecosystems.

Epidemiology

Fractional SIR models with memory effects produce better predictions of disease spread and intervention benefits in epidemiological modeling. The findings suggest that the inclusion of fractional models that take time-delayed responses in disease dynamics into consideration helps accurately predict, and therefore control strategies inklingies. This is especially important in understanding the convoluted transmission of diseases and considering how well public health measures work.

Financial Modeling

The Black-Scholes model of fractional generalization brings a new idea in the sphere of classical financial theories, namely behavioral aspects of asset pricing by incorporating fractional dynamics. The conclusion shows that a fractional derivative can fit to real data more accurately, not only it has ability of fitting well but retains volatility and price dynamics which traditional models cannot capture. Implications for Risk Management and Option Pricing – These findings provide a comprehensive, accurate prism in which to model risk management options or pricing strategies that help build forward performance forecasts.

Econometric Models

In econometrics, fractional ARFIMA models show the long-memory nature of many economic time series making it easier to forecast and analyze economic behavior. These results suggest that fractional models can better account accounting for the long-memory behavior of past values, and thus offer a more detailed description of longer-run economic trends and cycles.

DISCUSSION

Comparison to Classical Models

The advantages of fractional calculus in handling complex problems are very clearly illustrated bythe comparison between results obtained using fractional and classical models. There are many physical, microscopic and mesoscopic mechanisms embodying memory effects or non-standard dynamics which can be better characterized with fractional operators that account for the realization of both long and short memories in multi-dimensional interacting systems. This comparison highlights the potential of fractional calculus in handling phenomena that may be not properly described by classical integer-order models.

IMPLICATION FOR RESEARCH AND PRACTICE

This versatility makes it clear that applications of fractional order calculus in different fields may improve our understanding of complex systems. Fractional models provide new valuable insights and better predictions in different areas, from physics or engineering to biology and economics. The results show that we should include the derivative in the theoretical research and applications, as well obtain to complete previous studies of complex phenomena.

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Challenges and Limitations

Fractional calculus does have its advantages, yet it introduces some challenges. Fractional derivatives can be complicated to interpret and apply, often requiring domain-specific knowledge as well as computational resources. These new parameters introduced in fractional models might be making their fitting and interpretation messy. These challenges need to be addressed for both the advancement of fractional calculus as well in order that greater good can come from using it across various domains.

Future Directions

Future studies shall improve the methods of calculation in fractional calculus, new model fitting techniques and applications. Combining these derivations with the novel methods of other advanced mathematical methodologies like ML and optimization algorithms have far more increased possibilities for fractional calculus. Fractional calculus and other scientific fields with interdisciplinary approaches could provide new perspectives, strengthening fractional calculus in the union of theory as well practical applications.

CONCLUSION

The investigation and analysis of the fractional calculus models showed us a great potential to help in understanding more phenomena about complex systems. Through detailed analysis in this paper, we illustrate the benefits of fractional models from diverse domains and specifically describe how these can help to handle phenomena unfaithfully captured by classical model. Concurrently, fractional calculus research and subsequent developments will provide additional analyses to help establish more dependable models, assist with predictions that are closer to actual results through improved preparation in various fields.

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